CNN-based tools development

P. Płoński, D. Stefan, R. Sulej and seems others are joining





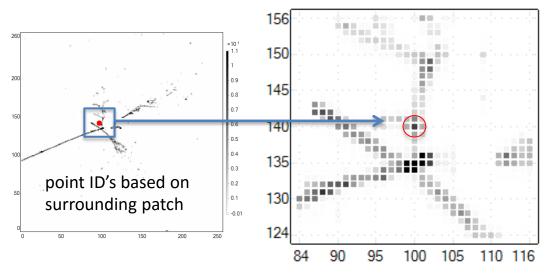


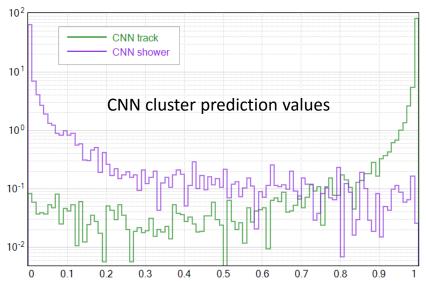


- basic idea, first application: EM vs. track-like ID
- implementations in / outside LArSoft
- list of tasks for the next weeks, and longer term

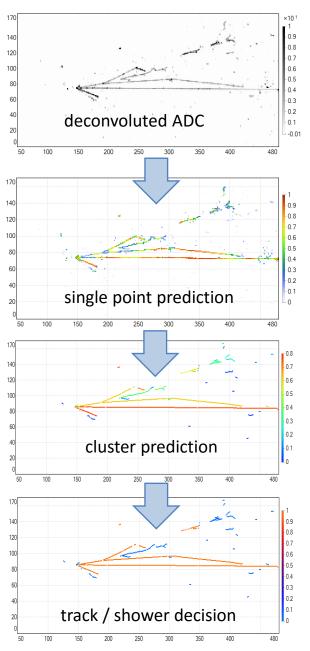
Basic idea: support standard reco, now used for EM-like / track-like cluster identification:

(as usual, old CNN on these pictures!)



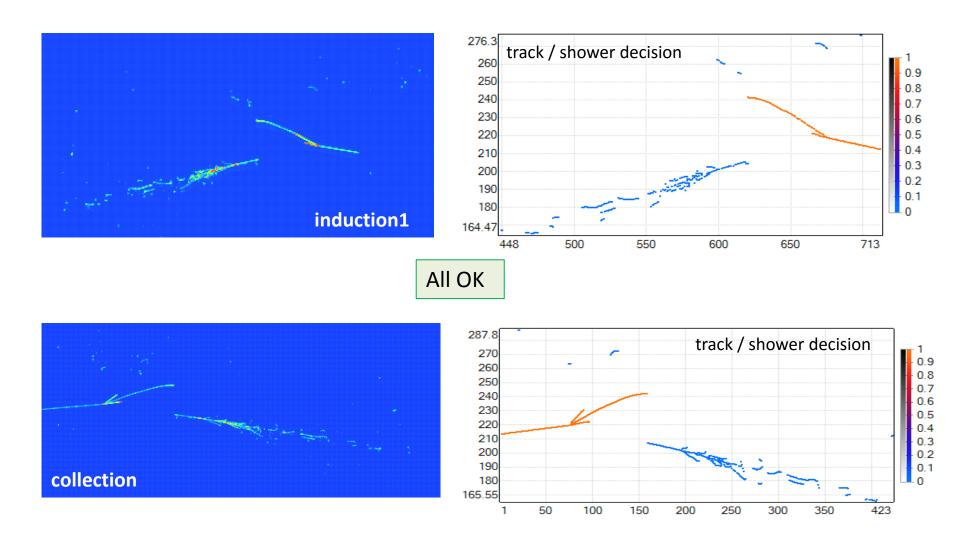


EM-like / track-like flow:



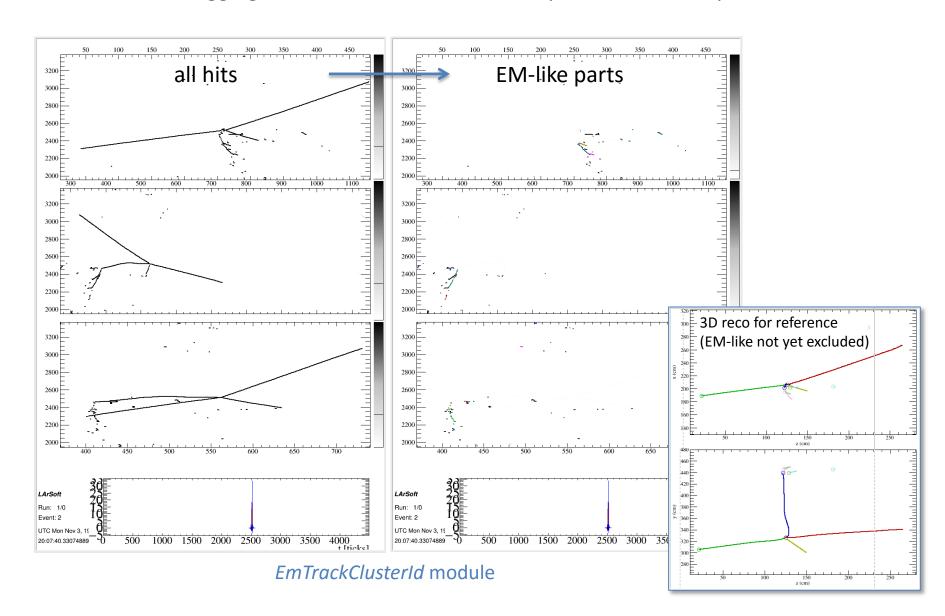
CNN results as of today: π^+ 2 GeV/c in protoDUNE SP

96.2% track / **96.6%** EM correct cluster ID rate (2GeV/c π ⁺ in protoDUNE)



CNN results as of today: π^+ 2 GeV/c in protoDUNE SP

module for tagging clusters and unclustered hits pushed to develop



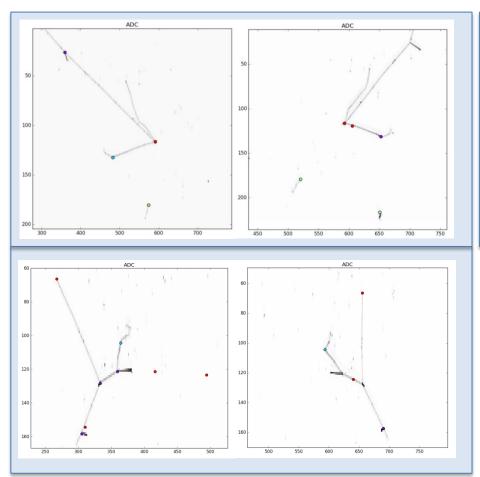
EM/track ID: data sizes...

- now used patch 32x32 (DUNE, 5mm pitch, downscale x10, needed square patch)
 = 16cm x 19cm
 - need large enough context and level of details
 - need similar size in wires and drift
 - need enough topologies for training (~5-8M patches / ~10k events was OK)
 - → O(10GB) training set (and larger files in the preparation stages...)
- Larger patch and drift resolution has more information for sure!
 - but GPU memory limitations are close...
 - and more border effects for larger patches
- rectangular patches are on the way (larreco feature/rnd HigherDriftResCNN)
 - includes also downsampling other than max-pool
- 4mm, area 16cm²: patch 40x40, downscale x6
 - → will start from these parameters, already a bit more drift resolution

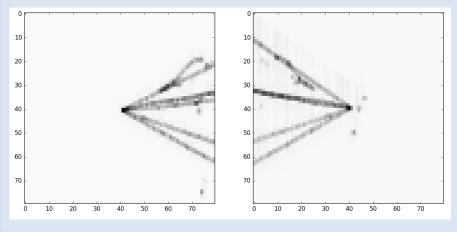
Vertex classification: similar "basic block" to EM/track ID

- Vertex identification
- support tracking with interaction/decay finding
- select EM shower starting points (not trivial in low energy)

- Neutrino interaction classification
- force classifier to be focused on the vertex features
- try to be sensitive to the "gap" in full neutrino events



data preparation module ~ready, need to verify thresholds to be tuned for reasonable visibility criteria



- need more events to build training set (only 1 training image pair/triplet per 1 event)
- more complex (than very simple) CNN may be needed
- uses larger patch arount the vertex and less downsampled drift
- more careful when producing data files to avoid really huge volumes...

How to approach work for the next weeks (LArIAT, protoDUNE, DUNE v's – very close)

- EM/track ID: need "LArIAT" model (= 4mm pitch)
- Vertex / decay point ID / classification: data prep needs last tuning of MC truth use



- Prepare (downscaled) wire dumps from MC (in LArSoft)
 - these files are <u>our starting point</u> to make all variations of training sets for EM/track and Vtx ID tasks → carefully
 - they are downsampled ROI's: small enough to move around the world
 - when needed: prepare next sets with different downsampling method / scale



- Make training / testing (no LArSoft, Python scripts: big big data sets, GPU training)
 - first set: patch size / downsample method and scale; make first CNN
 - more sets: play with statistics, training target definition; make useful/not overtrained CNN
- Test (back in LArSoft)
 - systematic checks: noise, amplitude impact, MC/data, ...
- Massive automatic search for optimal architecture / training method

More work...

- EM/track ID
- Vertex / decay point ID / classification

Dorota, Jessica, Robert

Neutrino vertex classification

Dorota (need another approach to make data, and DUNE work...)

Systematic effects

...likely will become a big task, start training yourself now

Model / trainig optimization

- Piotr and his MLJAR framework
- Data product design (vector of PID values, +some description, to be assigned to hits & clusters)

Other approaches: longer term

- RNN for localization of e.g. decaying μ
- Combine patch-size CNN with larger context
- Tensorflow interface to LArSoft